

Computer Organization and Architecture

Introduction

Architecture & Organization 1

⌘ Architecture is those attributes visible to the programmer

☒ Instruction set, number of bits used for data representation, I/O mechanisms, addressing techniques.

☒ e.g. Is there a multiply instruction?

⌘ Organization is how features are implemented, typically hidden from the programmer

☒ Control signals, interfaces, memory technology.

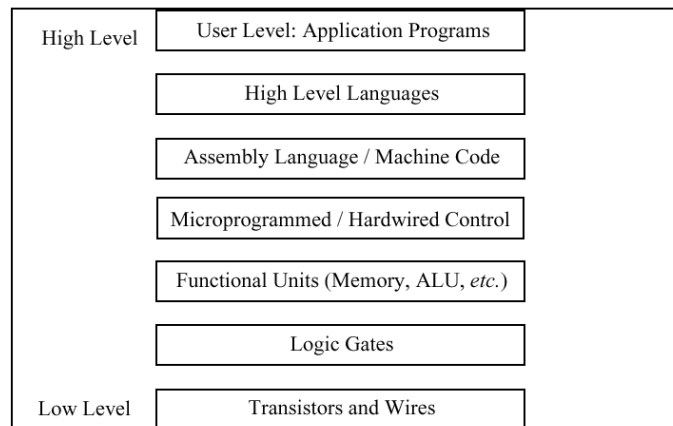
☒ e.g. Is there a hardware multiply unit or is it done by repeated addition?

Architecture & Organization 2

- ⌘ All Intel x86 family share the same basic architecture
- ⌘ The IBM System/370 family share the same basic architecture
- ⌘ This gives code compatibility
 - ☑ At least backwards
 - ☑ But... increases complexity of each new generation. May be more efficient to start over with a new technology, e.g. RISC vs. CISC
- ⌘ Organization differs between different versions

Levels of Machines

Computers are complex; easier to understand if broken up into hierarchical components.



Structure & Function

⌘ At each level the designer should consider

- ☒ **Structure** : the way in which components relate to each other
- ☒ **Function** : the operation of individual components as part of the structure

⌘ Let's look at the computer hardware top-down starting with function.

- ☒ Later we'll look at software

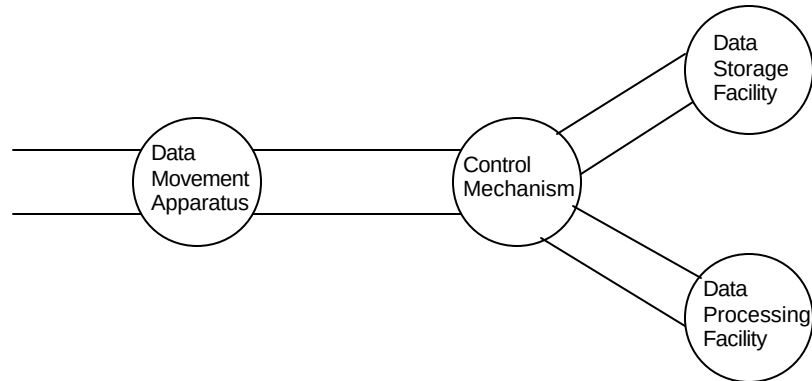
Function

⌘ All computer functions are:

- ☒ Data processing
- ☒ Data storage
- ☒ Data movement
- ☒ Control

Functional view

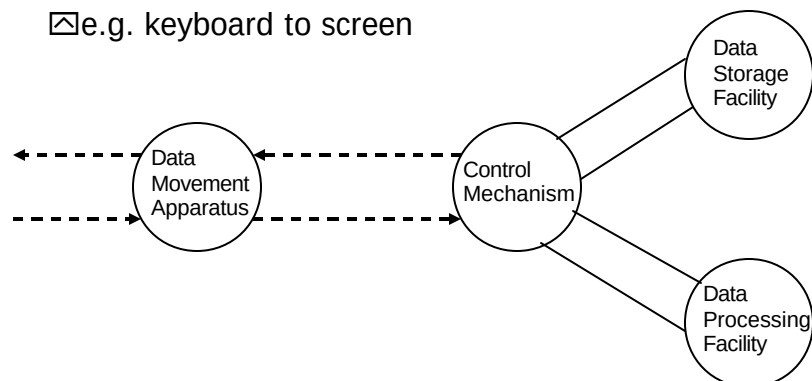
⌘ Functional view of a computer



Operations (1)

⌘ Data movement

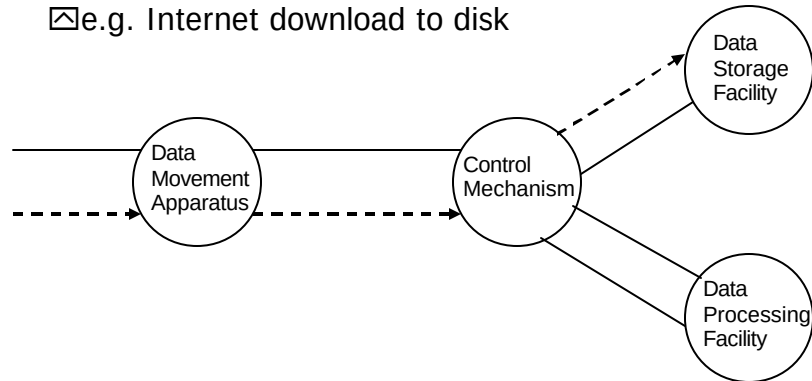
☒ e.g. keyboard to screen



Operations (2)

⌘ Storage

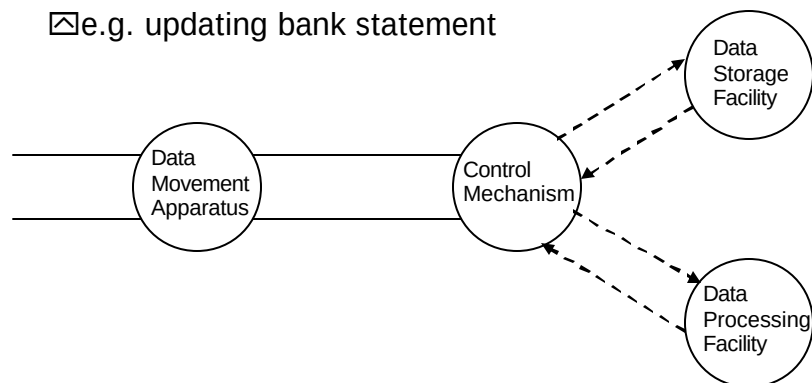
☒ e.g. Internet download to disk



Operation (3)

⌘ Processing from/to storage

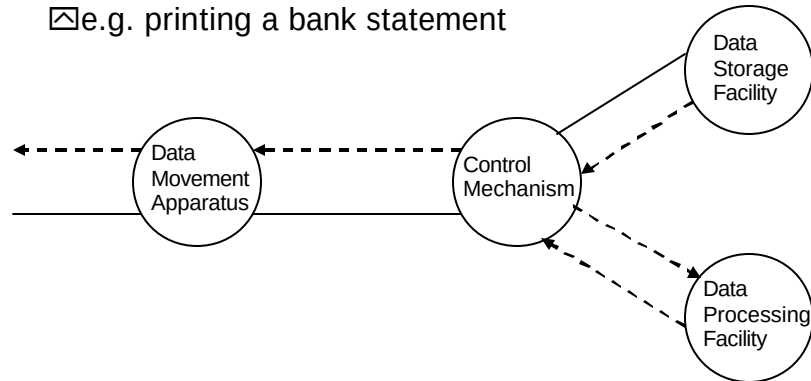
☒ e.g. updating bank statement



Operation (4)

⌘ Processing from storage to I/O

☒ e.g. printing a bank statement

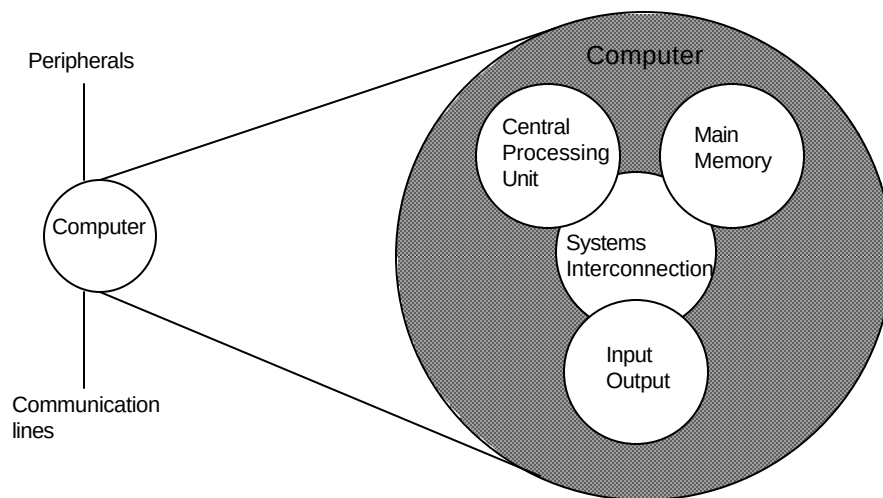


Structure

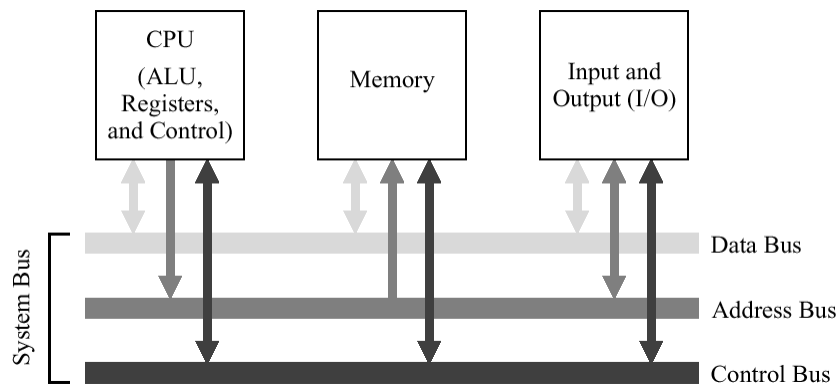
⌘ Major Components of a Computer

- ☒ Central Processing Unit (CPU) – Controls the operation of the computer and performs data processing
- ☒ Main Memory – Stores data
- ☒ Input Output (I/O) – Moves data between the computer and the external environment
- ☒ System Interconnect – Some mechanism that provides for communications between the system components, typically a **bus** (set of wires)

Structure - Top Level



Generic System Bus



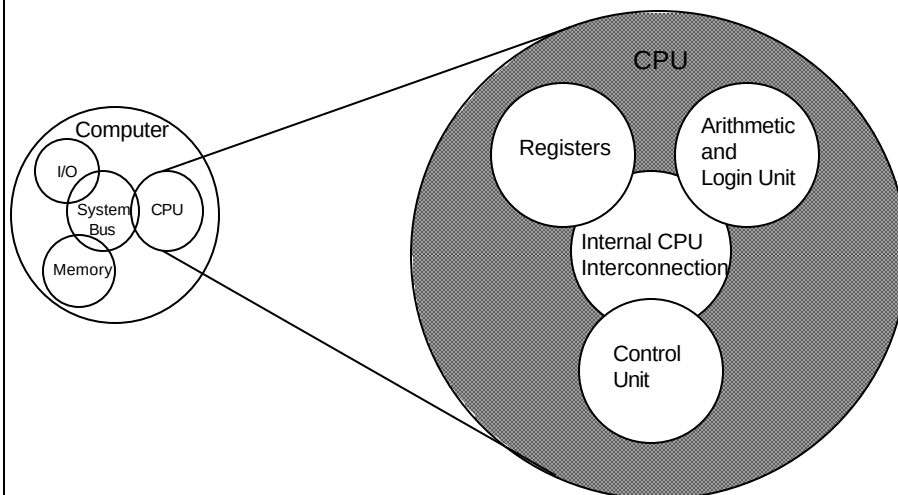
System Bus = Data, Address, and Control Bus (set of wires, e.g. 32 wires each)
Typically multiple I/O buses, power bus, etc.

Structure - CPU

⌘ Major components of the CPU

- ☒ Control Unit (CU) – Controls the operation of the CPU
- ☒ Arithmetic and Logic Unit (ALU) – Performs data processing functions, e.g. arithmetic operations
- ☒ Registers – Fast storage internal to the CPU, but contents can be copied to/from main memory
- ☒ CPU Interconnect – Some mechanism that provides for communication among the control unit, ALU, and registers

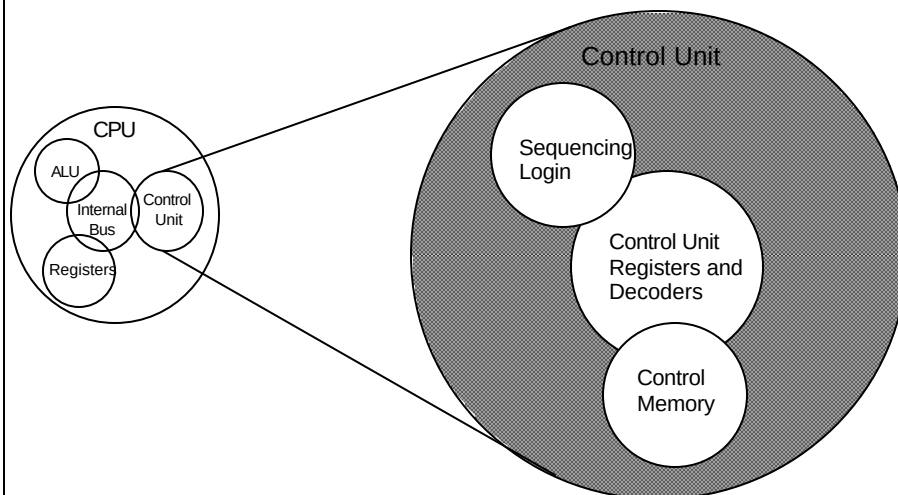
Structure - The CPU



Structure – Inside the CPU

- ⌘ The implementation of registers and the ALU we will leave primarily to EE 241
- ⌘ We will say a bit about the architecture of the control unit, there are many possible approaches.
 - ☒ A common approach is the microprogrammed control unit, where the control unit is in essence itself a miniature computer, where a CPU instruction is implemented via one or more “micro instructions”
 - ☒ Sequencing Logic – Controlling the order of events
 - ☒ Microprogram Control Unit – Internal controls
 - ☒ Microprogram Registers, Memory

Structure – A Microprogrammed Control Unit



Computer Evolution and Performance

Better, Faster, Cheaper?

History: ENIAC background

- ⌘ Electronic Numerical Integrator And Computer
- ⌘ Eckert and Mauchly
- ⌘ University of Pennsylvania
- ⌘ Trajectory tables for weapons, BRL
- ⌘ Started 1943
- ⌘ Finished 1946
 - ☒ Too late for war effort
- ⌘ Used until 1955

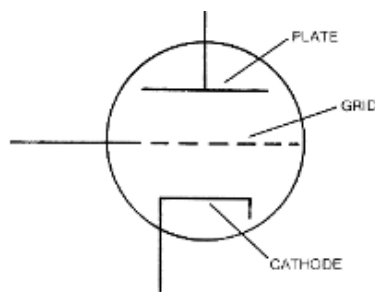
ENIAC - details

- ⌘ Decimal (not binary)
- ⌘ 20 accumulators of 10 digits (ring of 10 tubes)
- ⌘ Programmed manually by switches
- ⌘ 18,000 vacuum tubes
- ⌘ 30 tons
- ⌘ 15,000 square feet
- ⌘ 140 kW power consumption (about \$10/hr today)
- ⌘ 5,000 additions per second

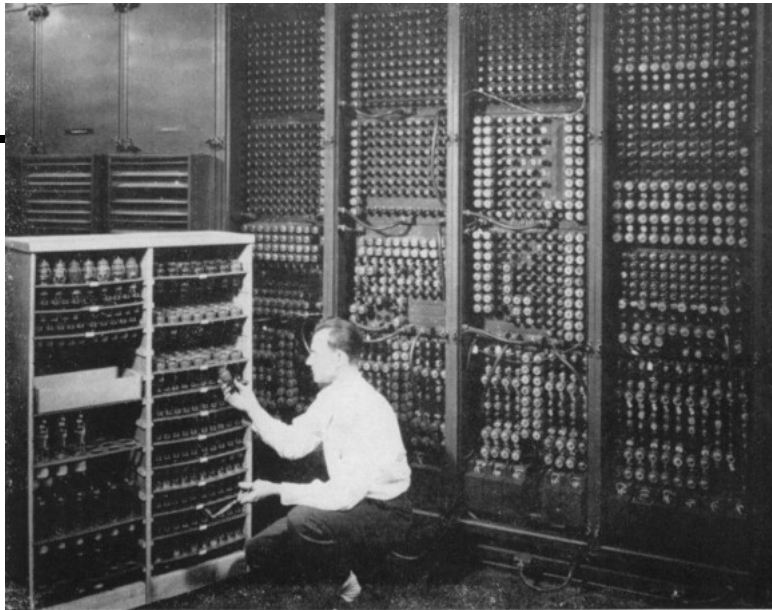
Vacuum Tubes



vacuum tube
from the early
1900's



Grid regulates flow from of electrons from the cathode



Replacing a bad tube meant checking among ENIAC's 19,000 possibilities.

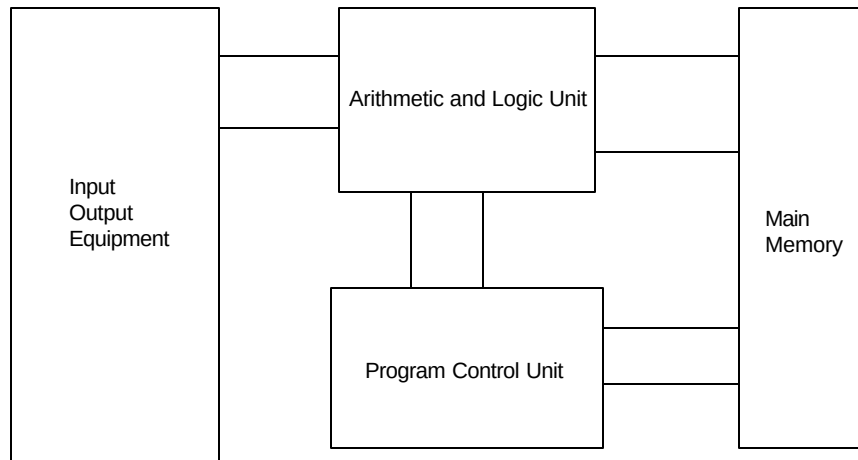
von Neumann/Turing

⌘ ENIAC : Very tedious to manually wire programs

⌘ von Neumann architecture:

- ☑ Stored Program concept
- ☑ Main memory storing programs and data
- ☑ ALU operating on binary data
- ☑ Control unit interpreting instructions from memory and executing
- ☑ Input and output equipment operated by control unit
- ☑ Princeton Institute for Advanced Studies
 - ☑ IAS
- ☑ Completed 1952

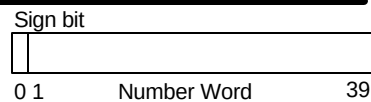
Structure of von Neumann machine



IAS - details

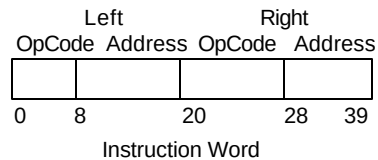
⌘ 1000 x 40 bit words

- ☒ Binary number
- ☒ 2 x 20 bit instructions

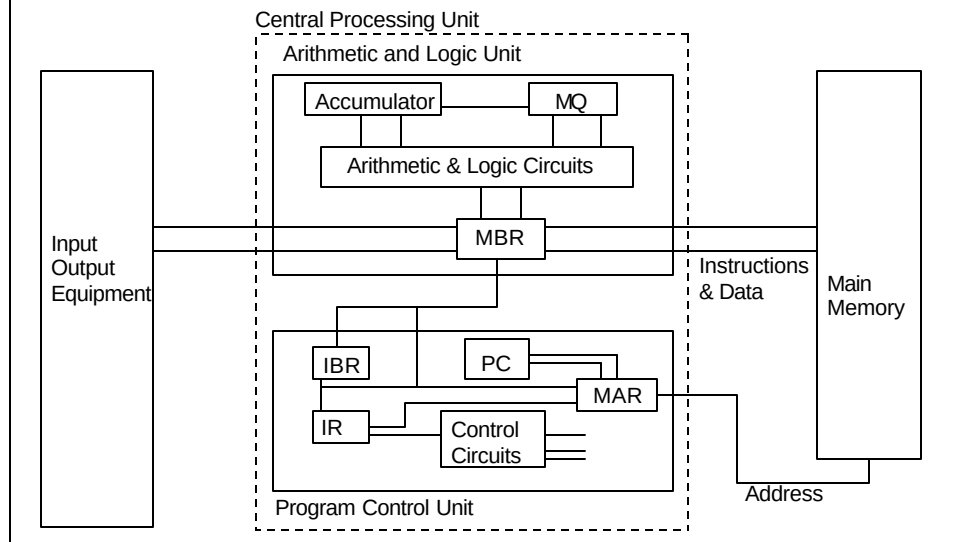


⌘ Set of registers (storage in CPU)

- ☒ Memory Buffer Register
- ☒ Memory Address Register
- ☒ Instruction Register
- ☒ Instruction Buffer Register
- ☒ Program Counter
- ☒ Accumulator
- ☒ Multiplier Quotient



Structure of IAS - detail



IAS Instruction Cycle

⌘ The IAS repetitively performs the instruction cycle:

☑ Fetch

- ☑ Opcode of the next instruction is loaded into the IR
- ☑ Address portion is loaded into the MAR
- ☑ Instruction either taken from the IBR or obtained from memory by loading the PC into the MAR, memory to the MBR, then the MBR to the IBR and the IR
 - To simplify electronics, only one data path from MBR to IR

☑ Execute

- ☑ Circuitry interprets the opcode and executes the instruction
- ☑ Moving data, performing an operation in the ALU, etc.

⌘ IAS had 21 instructions

- ☑ Data transfer, Unconditional branch, conditional branch, arithmetic, address modification

Commercial Computers

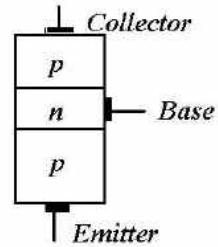
- ⌘ 1947 - Eckert-Mauchly Computer Corporation
- ⌘ UNIVAC I (Universal Automatic Computer)
- ⌘ US Bureau of Census 1950 calculations
- ⌘ Became part of Sperry-Rand Corporation
- ⌘ Late 1950s - UNIVAC II
 - ☑ Faster
 - ☑ More memory
 - ☑ Upward compatible with older machines

IBM

- ⌘ Punched-card processing equipment
- ⌘ 1953 - the 701
 - ☑ IBM's first stored program computer
 - ☑ Scientific calculations
- ⌘ 1955 - the 702
 - ☑ Business applications
- ⌘ Lead to 700/7000 series

Transistors

- ⌘ Replaced vacuum tubes
- ⌘ Smaller
- ⌘ Cheaper
- ⌘ Less heat dissipation
- ⌘ Solid State device
- ⌘ Made from Silicon (Sand)
- ⌘ Invented 1947 at Bell Labs
- ⌘ Shockley, Brittain, Bardeen



Transistor Based Computers

- ⌘ Second generation of machines
- ⌘ NCR & RCA produced small transistor machines
- ⌘ IBM 7000
- ⌘ DEC - 1957
 - ☒ Produced PDP-1

IBM 7094

⌘ Last member of the 7000 series

- ☒ 50 times faster than the 701
 - ☒ 1.4 μ S vs. 30 μ S cycle
- ☒ 32K memory vs. 2K
- ☒ Main memory: Core memory vs. Tubes
- ☒ CPU memory: transistors vs. Tubes
- ☒ 185 vs. 24 opcodes
- ☒ Instruction fetch overlap, reduced another trip to memory (exception are branches)
- ☒ Data channels, independent I/O module for devices

3rd Generation: Integrated Circuits

⌘ Self-contained transistor is a discrete component

- ☒ Big, manufactured separately, expensive, hot when you have thousands of them

⌘ Integrated Circuits

- ☒ Transistors “etched” into a substrate, bundled together instead of discrete components
- ☒ Allowed thousands of transistors to be packaged together efficiently

Microelectronics

- ⌘ Literally - “small electronics”
- ⌘ A computer is made up of gates, memory cells and interconnections
- ⌘ These can be manufactured on a semiconductor, e.g. silicon wafer
 - ☒ Thin wafer divided into chips
 - ☒ Each chip consists of many gates/memory cells
 - ☒ Chip packaged together with pins, assembled on a printed circuit board

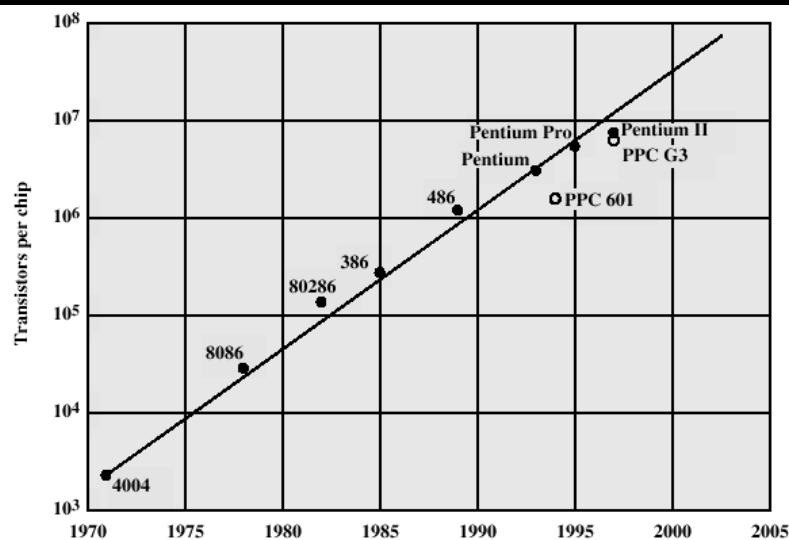
Generations of Computer

- ⌘ Vacuum tube - 1946-1957
- ⌘ Transistor - 1958-1964
- ⌘ Small scale integration - 1965 on
 - ☒ Up to 100 devices on a chip
- ⌘ Medium scale integration - to 1971
 - ☒ 100-3,000 devices on a chip
- ⌘ Large scale integration - 1971-1977
 - ☒ 3,000 - 100,000 devices on a chip
- ⌘ Very large scale integration - 1978 to date
 - ☒ 100,000 - 100,000,000 devices on a chip
 - ☒ Pentium IV has about 40 million transistors
- ⌘ Ultra large scale integration
 - ☒ Over 100,000,000 devices on a chip (vague term)

Moore's Law

- ⌘ Increased density of components on chip
- ⌘ Gordon Moore : co-founder of Intel
- ⌘ Number of transistors on a chip will double every year
- ⌘ Since 1970's development has slowed a little
 - ☐ Number of transistors doubles every 18 months
- ⌘ Cost of a chip has remained almost unchanged
- ⌘ Higher packing density means shorter electrical paths, giving higher performance
- ⌘ Smaller size gives increased flexibility
- ⌘ Reduced power and cooling requirements
- ⌘ Fewer interconnections increases reliability
- ⌘ Intel 8/13/02: Announced 0.09 micron process
 - ☐ Human hair ~70 microns

Growth in CPU Transistor Count



IBM 360 series

⌘ 1964

⌘ Replaced (& not compatible with) 7000 series

☒ Reason: Needed to break out of constraints of the 7000 architecture

⌘ First planned “family” of computers

☒ Similar or identical instruction sets

☒ Similar or identical O/S

☒ Increasing speed

☒ Increasing number of I/O ports (i.e. more terminals)

☒ Increased memory size

☒ Increased cost (not always the case today!)

⌘ Multiplexed switch structure

DEC PDP-8

⌘ 1964

⌘ First minicomputer (after miniskirt!)

⌘ Did not need air conditioned room

⌘ Small enough to sit on a lab bench

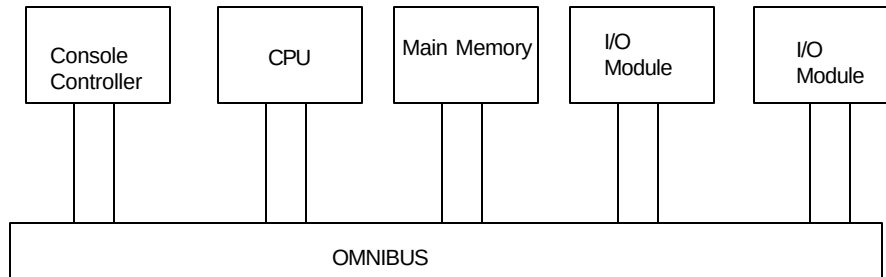
⌘ \$16,000

☒ \$100k+ for IBM 360

⌘ Embedded applications & OEM

⌘ BUS STRUCTURE

DEC - PDP-8 Bus Structure



96 separate signal paths to carry control, address, data signals
Highly flexible, allowed modules to be plugged in for different configurations

Other Innovations - Semiconductor Memory

- ⌘ 1970

- ⌘ Fairchild

- ⌘ Size of a single core

 - ☒ i.e. 1 bit of magnetic core storage

 - ☒ Held 256 bits

- ⌘ Non-destructive read

- ⌘ Much faster than core

- ⌘ Capacity approximately doubles each year

Intel

⌘ 1971 - 4004

- ☑ First microprocessor
- ☑ All CPU components on a single chip
- ☑ 4 bit

⌘ Followed in 1972 by 8008

- ☑ 8 bit
- ☑ Both designed for specific applications

⌘ 1974 - 8080

- ☑ Intel's first general purpose microprocessor

⌘ Evolution: 8086, 8088, 80286, 80386, 80486, Pentium Pentium Pro, Pentium II, Pentium III, Pentium IV, Itanium

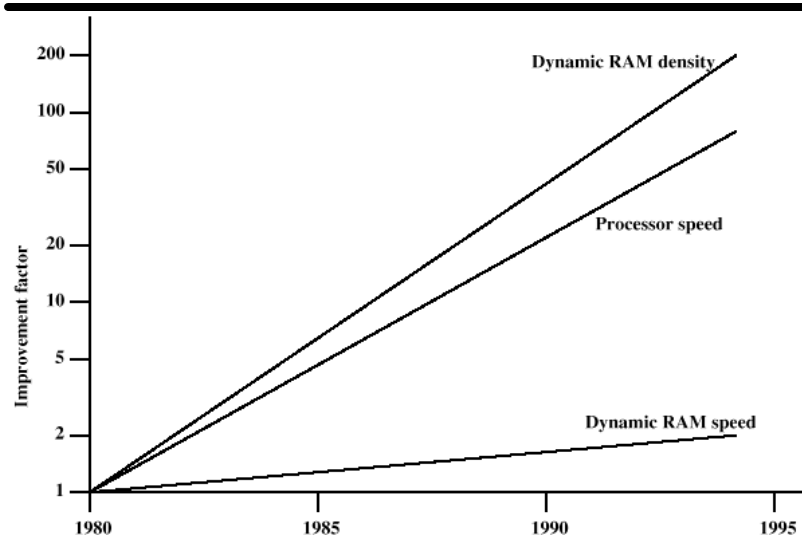
Speeding it up

- ⌘ Smaller manufacturing process (0.09 micron)
- ⌘ Pipelining
- ⌘ On board cache
- ⌘ On board L1 & L2 cache
- ⌘ Branch prediction
- ⌘ Data flow analysis
- ⌘ Speculative execution
- ⌘ Parallel execution

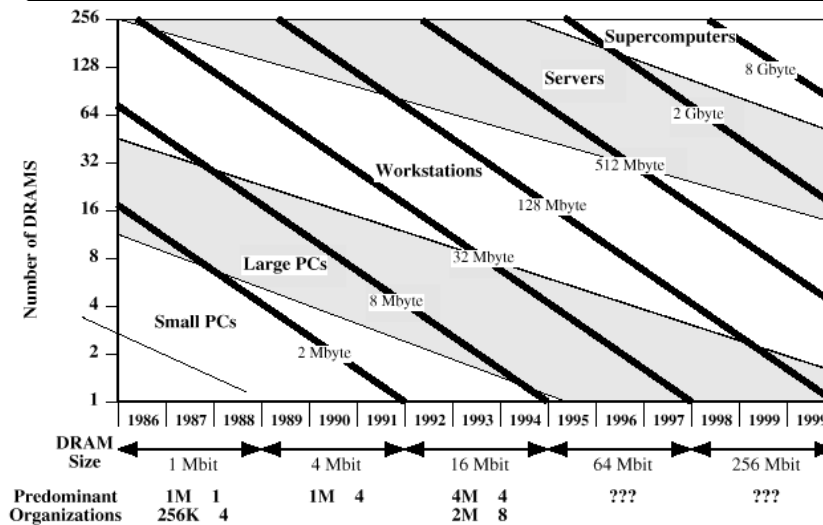
Performance Mismatch

- ⌘ Processor speed increased
- ⌘ Memory capacity increased
- ⌘ Memory speed lags behind processor speed
- ⌘ Common memory chip technology
 - ☐ DRAM = Dynamic Random Access Memory

DRAM and Processor Characteristics



Trends in DRAM use



Solutions

- ⌘ Increase number of bits retrieved at one time
 - ☐ Make DRAM “wider” rather than “deeper”
- ⌘ Change DRAM interface
 - ☐ Cache
- ⌘ Reduce frequency of memory access
 - ☐ More complex cache and cache on chip
- ⌘ Increase interconnection bandwidth
 - ☐ High speed buses
 - ☐ Hierarchy of buses
- ⌘ Similar problems with I/O devices, e.g. graphics, network
- ⌘ Need balance in computer design